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ASYMPTOTE OF THE NAVIER-STOKES EQUATION SOLUTION IN THE VICINITY OF A BOUNDARY ANGLE

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In a study of single-sided limitations for the Navier-Stokes equations, [1] considered the function $\psi(r, \varphi)$, which satisfies the equation

$$\Delta \Delta \psi = 0, \ r < \varepsilon, \ -\pi < \varphi < 0 \tag{1}$$

(where $\varepsilon > 0$ is a constant) with boundary conditions

$$\begin{split} \psi &= 0, \ \Delta \psi = 0, \ \varphi = 0, \ 0 < r < \varepsilon, \\ \psi &= 0, \ \frac{\partial \psi}{\partial \varphi} = r, \ \varphi = -\pi, \ 0 < r < \varepsilon. \end{split}$$

Here (r, φ) is a planar polar coordinate system and Δ is the Laplace operator. In addition we assume the function belongs to the Sobolev space W_2^2 in the semicircle $S_{\varepsilon} = \{(r, \varphi) : r < \varepsilon, -\pi < \varphi < 0\}$. Using the method developed in [2, 3] the authors presented the expression

$$\psi = -r\sin\varphi + Ar^{3/2}\left(\sin\frac{\varphi}{2} + \sin\frac{3\varphi}{2}\right) + O(r^2\ln r)$$
⁽²⁾

for $r \to 0$, $-\pi < \varphi < 0$, A = const, which is dependent on ψ . Asymptotic representations of $\partial \psi / \partial r$, $\partial \psi / \partial \varphi$, $\Delta \psi$ can be obtained from Eq. (2) by formal differentiation. In fact, Eq. (2) can be refined: for ψ one can expand in an asymptotic series [2, 4]

$$\psi = -r\sin\varphi t \sum_{j=3}^{\infty} A_j r^{j/2} \Phi_j(\varphi), \quad A_j = \text{const},$$
(3)

where Φ_j are eigenfunctions, normalized in $L_2[-\pi, 0]$, of the problem

$$\frac{1}{4}j^{2}\left(\frac{j}{2}-2\right)^{2}\Phi+\frac{j^{2}}{2}\Phi'''+\Phi^{\mathrm{IV}}=0,$$

-\pi <\pi <0, \Phi(-\pi) = \Phi(0) = 0, \Phi'(-\pi) = \Phi''(0) = 0. (4)

Equation (3) is asymptotic in the sense that no matter what the value of N, the estimates

$$\left| D^{\alpha}(\mathbf{\psi}) + r \sin \varphi - \sum_{j=3}^{N} A_{j} r^{j/2} \Phi_{j}(\mathbf{\varphi}) \right| = O(r^{(N+1)/2 - |\alpha|})$$

are valid as $r \to 0$ for all α . Here $D^{\alpha} = \partial^{|\alpha|} / \partial x_1^{\alpha_1} \partial x_2^{\alpha_2}$; $|\alpha| = \alpha_1 + \alpha_2$. Note that Eq. (4) with constant coefficients is easily solved and the eigenfunctions of Eq. (4) can be written explicity; Equation (3) is a special case of a more general expression which gives the asymptotic representation of a boundary problem for an arbitrary elliptic equation in the vicinity of an angular point on the region's boundary. It follows from Eq. (3) that in Eq. (2) the

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residual term can be replaced by $O(r^2)$, and its second derivatives are finite. In [4], which was used in [1] in deriving Eq. (2), it was not Eq. (1), but the nonlinear Navier-Stokes equation

$$\mathbf{v}\Delta\Delta u + \frac{\partial u}{\partial x}\frac{\partial\Delta u}{\partial y} - \frac{\partial u}{\partial y}\frac{\partial\Delta u}{\partial x} = 0, \quad r < \varepsilon, \quad 0 < \varphi < 2\pi$$
(5)

which was studied with boundary conditions

$$u = \frac{\partial u}{\partial \varphi} = 0, \quad \varphi = 0, \quad \varphi = 2\pi, \quad 0 < r < \varepsilon.$$
(6)

It was assumed that $u \in W_2^2(S_{\varepsilon})$, $S_{\varepsilon} = \{x : 0 < \phi < 2\pi, 0 < r < \varepsilon\}$. We will call the generalized solution of Eqs. (5), (6) the function $u(x) \in W_2^2(S_{\varepsilon})$, satisfying boundary conditions (6), and such that

$$\mathbf{v} \int_{\mathbf{S}_{\mathbf{E}}} \left[\frac{\partial^2 u}{\partial x_1^2} \frac{\partial^2 \psi}{\partial x_1^2} + 2 \frac{\partial^2 u}{\partial x_1 \partial x_2} \frac{\partial^2 \psi}{\partial x_1 \partial x_2} + \frac{\partial^2 u}{\partial x_2^2} \frac{\partial^2 \psi}{\partial x_2^2} \right] dx_1 dx_2 + \int_{\mathbf{S}_{\mathbf{E}}} \Delta u \left(\frac{\partial \psi}{\partial x_1} \frac{\partial u}{\partial x_2} \left(- \frac{\partial \psi}{\partial x_2} \frac{\partial u}{\partial x_1} \right) dx_1 dx_2 = 0$$

for any $\psi(x) \in \mathring{W}_2^2(S_{\varepsilon})$.

In reality, the representation of Eq. (2) with residual term of the order of $O(r^2)$ can also be obtained for the solution of Eqs. (5), (6). In doing this we will make use of results from estimates $L_p(1 of the boundary problem solutions of [5], which were not known at the time that [3] appeared. It was proved in [5] that if <math>u(x)$ is a generalized solution of the equation

$$\Delta \Delta u = \frac{\partial f_1}{\partial x_1} + \frac{\partial f_2}{\partial x_2}$$

in S_{ε} , satisfying boundary conditions (6),

$$u(x) \in W_q^2(S_{\varepsilon}), \quad q \ge 2, \quad \int_{S_{\varepsilon}} |f_i|^p dx_1 dx_2 < \infty, \quad p > 1, \quad i = 1, 2,$$

then

$$u(x) = Ar^{3/2} \left(\sin \frac{\varphi}{2} + \sin \frac{3\varphi}{2} \right) + u_0(x), \tag{7}$$

where

$$\|u_0\|_{W_p^3(S_{\ell/2})}^2 \leqslant C \left[\sum_{i=1}^2 \|f_i\|_{L_p(S_{\ell})}^2 + \|u\|_{L_2(S_{\ell})}^2 \right], \quad 1$$

and

$$u(x) = Ar^{3/2} \left(\sin \frac{\varphi}{2} + \sin \frac{3\varphi}{2} \right) + Br^2 \sin^2 \varphi + u_g(x).$$
(8)

Here

$$\|u_0(x)\|_{W^3_p(S_{\varepsilon/2})} \leq C \left[\|u\|_{L_2(S_{\varepsilon})} + \sum_{i=1}^2 \|f_i\|_{L_p(S_{\varepsilon})} \right].$$

Moreover,

$$|A| \leqslant C \left[\|u\|_{L_{2}(S_{\varepsilon})} + \sum_{i=1}^{2} \|f_{i}\|_{L_{p}(S_{\varepsilon})} \right] \text{ for } 1
$$|A| + |B| \leqslant C \left[\|u\|_{L_{2}(S_{\varepsilon})} + \sum_{i=1}^{2} \|f_{i}\|_{L_{p}(S_{\varepsilon})} \right] \text{ for } 2
to study the problem of Eqs. (5) and (6)$$$$

This result can be used to study the problem of Eqs. (5) and (6).

<u>Theorem</u>. If $u(x) \in W_2^2(S_{\varepsilon})$ is a solution of the problem of Eqs. (5), (6), then u(x) has the form of Eq. (8), where

$$\sum_{0 \le h_1 + h_2 = h \le 2} \left| \frac{\partial^h u_0(x)}{\partial x_1^{h_1} \partial x_2^{h_2}} \right| \le C \| u \|_{W_2^2(S_{\mathcal{E}})},$$
(9)

 $x \in S_{\rm c}/_{\rm 4}$, C = const, of which the solution is independent.

<u>Proof</u>. Equation (5) can be written in the form

$$v\Delta\Delta u = -\frac{\partial}{\partial x_2} \left(\frac{\partial u}{\partial x_1} \Delta u \right) + \frac{\partial}{\partial x_1} \left(\Delta u \frac{\partial u}{\partial x_2} \right) = \frac{\partial f_1}{\partial x_1} + \frac{\partial f_2}{\partial x_2}.$$
 (10)

Here $f_1 \in L_s(\Omega_{\epsilon}), f_2 \in L_s(\Omega_{\epsilon})$ for any s < 2, since $\Delta u \in L_2(\Omega_{\epsilon})$, grad $u \in L_p(\Omega_{\epsilon})$ for any p < ∞ . Thus, Eq. (7) is valid for u(x), where u₀(x) satisfies the inequality

$$\sum_{k_1+k_2=3} \left\| \frac{\partial^3 u_n}{\partial x_1^{k_1} \partial x_2^{k_2}} \right\|_{L_p(S_{\ell/2})} \leqslant C_p \| u \|_{W_2^2(S_{\ell})} \quad \forall p < 2.$$
(11)

From Eq. (11) and the Sobolev inclusion theorem it follows that $u_0 \in W^2_q(S_{\epsilon/2})$, $u_0 \in C^1(S_{\epsilon/2})$ for any q. Representing u in the form of Eq. (7) in Eq. (10), for u_0 we obtain

$$v\Delta\Delta u_0 = \frac{\partial}{\partial x_1}F_1 + \frac{\partial}{\partial x_2}F_2,$$

where $F_1 \in L_p(S_{\epsilon/2})$, $F_2 \in L_p(S_{\epsilon/2})$ for any p < 4 and

$$\|F_1\|_{L_p(S_{\epsilon/2})} + \|F_2\|_{L_p(S_{\epsilon/2})} \leq C \|u\|_{W_2^2(S_{\epsilon})}.$$

Using Eq. (8) for u_0 , we have

$$u_0 = A_1 r^{3/2} \left(\sin \frac{\varphi}{2} + \sin \frac{3\varphi}{2} \right) + B_1 r^2 \sin^2 \varphi + v_0(x).$$
(12)

Here $v_0(x) \in W_p^3(S_{\varepsilon/4})$ for any p < 4. From the Sobolev inclusion theorem we now know that $v_0 \in C^2(S_{\varepsilon/4})$. Substituting u_0 in the form of Eq. (12) in Eq. (7) we find the required Eq. (9), where $v_0 \in C^2(S_{\varepsilon/4})$.

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